

METHODOLOGY ARTICLE

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On the simple calculation of walking efficiency without kinematic information for its convenient use

Daijiro Abe^{1*}, Yoshiyuki Fukuoka² and Masahiro Horiuchi³

Abstract

Background: Since walking is a daily activity not to require the maximal effort in healthy populations, a very few universal bio-parameters and/or methods have been defined to evaluate individual walking characteristics in those populations. A concept of “economy” is a potential candidate; however, walking economy highly depends on speed, so direct comparisons of economy values are difficult between studies. We investigated whether the vertical component of net walking “efficiency” (Eff_{vert} ; %) is constant across speed. In that case, direct comparisons of Eff_{vert} will be possible between studies or individuals at any voluntary speed.

Methods: Thirty young male participants walked at eight speeds on the level or $\pm 5\%$ gradients, providing vertical speeds (v_{vert}). Differences in energy expenditure between level and uphill or downhill gradients (ΔEE) were calculated. The metabolic rate for vertical component (MR_{vert}) was calculated by multiplying ΔEE with body mass (BM). The mechanical power output for vertical component (P_{mech}) was calculated by multiplying BM, gravitational acceleration, and v_{vert} . Eff_{vert} was obtained from the ratio of P_{mech} to MR_{vert} at each v_{vert} . Delta efficiency (Delta-E; %) was also calculated from the inverse slope of the regression line representing the relationship of P_{mech} to MR_{vert} .

Results: Upward Eff_{vert} was nearly constant at around 35% and downward Eff_{vert} ranged widely (49–80%). No significant differences were observed between upward Delta-E ($35.5 \pm 8.8\%$) and Eff_{vert} at any speeds, but not between downward Delta-E ($44.9 \pm 12.8\%$) and Eff_{vert} .

Conclusions: Upward ΔEE could be proportional to v_{vert} . Upward, but not downward, Eff_{vert} should be useful not only for healthy populations but also for clinical patients to evaluate individual gait characteristics, because it requires only two metabolic measurements on the level and uphill gradients without kinematic information at any voluntary speed.

Trial registration: UMIN000017690 (R000020501; registered May 26th, 2015, before the first trial) and UMIN000031456 (R000035911; registered Feb. 23rd, 2018, before the first trial).

Keywords: Bipedalism, Locomotion, Gait, Model analysis

Background

Walking and running are two of the major gait patterns in the erect bipedal locomotion. Previous literatures have evaluated individual running capacities using already established physiological parameters. However, except for race walking, walking is a daily activity not to require individual maximal effort, so relatively fewer biomechanical parameters or methods have been developed to

evaluate individual walking characteristics in healthy populations and clinical patients [1]. A concept of “efficiency” is a potential and universal candidate; however, the evaluation of walking efficiency takes considerable technical effort because of the need to process kinematic information using expensive devices and specialized software [1, 2]. Nevertheless, it still involves various uncertainties in the quantification of the mechanical work done by multiple body segments (internal work), as well as the “negative” work [2]. Thus, literatures often use the concept of “economy,” the energy cost of transport per unit distance (CoT; $J \cdot \text{kg}^{-1} \cdot \text{km}^{-1}$), because this only requires metabolic information [3]. However, walking

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economy is highly dependent on speed, with a U-shaped relationship between CoT values and walking speed [4–7]. Thus, as far as we know, the economical speed could be the only index for evaluating walking ability in each individual [4–11]. However, it is difficult to measure the entire CoT-speed curve for people with poor physical fitness, such as patients after surgery [8], elderly populations [7, 9, 10], and pregnant women [11], for safety considerations. This may limit the number of metabolic measurements only at slower speeds. Differences in walking speed also make it difficult to directly compare economy values between studies.

For a given walking speed, whole-body energy expenditure (EE; $\text{J}\cdot\text{kg}^{-1}\cdot\text{s}^{-1}$) differs between the level and uphill/downhill gradients (ΔEE ; $\text{J}\cdot\text{kg}^{-1}\cdot\text{s}^{-1}$); thus, the vertical component of metabolic rate (MR_{vert} ; watt) can be obtained by multiplying ΔEE with body mass (BM; kg). The vertical component of mechanical power output (P_{mech} ; watt) can be calculated by multiplying BM, gravitational acceleration (g ; $\text{m}\cdot\text{s}^{-2}$), and the vertical component of walking speed (v_{vert} ; $\text{m}\cdot\text{s}^{-1}$) [12–16]. The ratio of the P_{mech} to MR_{vert} gives the vertical component of net walking efficiency (Eff_{vert} ; %). Here, Eff_{vert} at each speed will be possible to calculate without kinematic information.

The net “horizontal” walking efficiency calculated from both metabolic and kinematic information has varied widely between literatures (25–40%) [17–20]. It has also been reported to have an inverse U-shaped profile as a function of horizontal walking speed [18, 20]. In contrast, Eff_{vert} as a function of speed has been estimated to be constant for each individual during uphill running [21] and climbing ergometer exercise [22]. This is because the EE required to lift the body was proportional to the gradient when walking at a given speed [23]. If Eff_{vert} is constant across speeds, then an assessment of Eff_{vert} requires only two metabolic measurements while walking at any voluntary speed along the level and a gentle uphill gradient. Indeed, several previous studies have used Eff_{vert} to evaluate effects of maximal strength training on gait characteristics in elderly cardiorespiratory patients [13, 14], schizophrenia patients with gait disturbance [12], and healthy elderly populations [16]. The metabolic measurement in those studies was always conducted at a particular speed ($1.0\text{ m}\cdot\text{s}^{-1}$); however, only one study measured healthy young populations [16], suggesting that we merely know about a potential usage of Eff_{vert} for other populations, particularly at faster walking speeds.

Delta efficiency (Delta-E; %), defined as the inverse slope of the regression line representing the relationship of mechanical power output to energy consumption rate, might also be useful for evaluating walking efficiency “without” kinematic information. Although

Delta-E has been used for running in previous studies (e.g., [21]), it still requires several sets of metabolic measurements. There has been limited information for evaluating both Eff_{vert} and Delta-E for walking [24, 25]. For an individual, there is only one Delta-E value for each gradient, so it is impossible to evaluate whether Eff_{vert} is dependent on v_{vert} . It is interesting to note that downhill Eff_{vert} gradually decreases as a function of walking speed [25]. This could be due to changes in the recovery rate of pendular energy transduction between kinetic energy and gravitational potential energy [2, 25, 26] and greater eccentric muscle contractions during downhill walking, being associated with the utilization of stored elastic energy [19, 20, 25]. Contrary to downhill walking, uphill walking makes us more exhausted compared to level walking, because more “positive” work in the exercising muscles is necessary during uphill walking than level or downhill walking [25]. We hypothesized that upward, but not downward, Eff_{vert} values would be constant across various v_{vert} . To test this hypothesis and to expand a potential procedure of previous studies [12–16, 21, 23, 24], the aim of this study was to obtain Eff_{vert} and Delta-E values for a range of v_{vert} in healthy young participants without kinematic information.

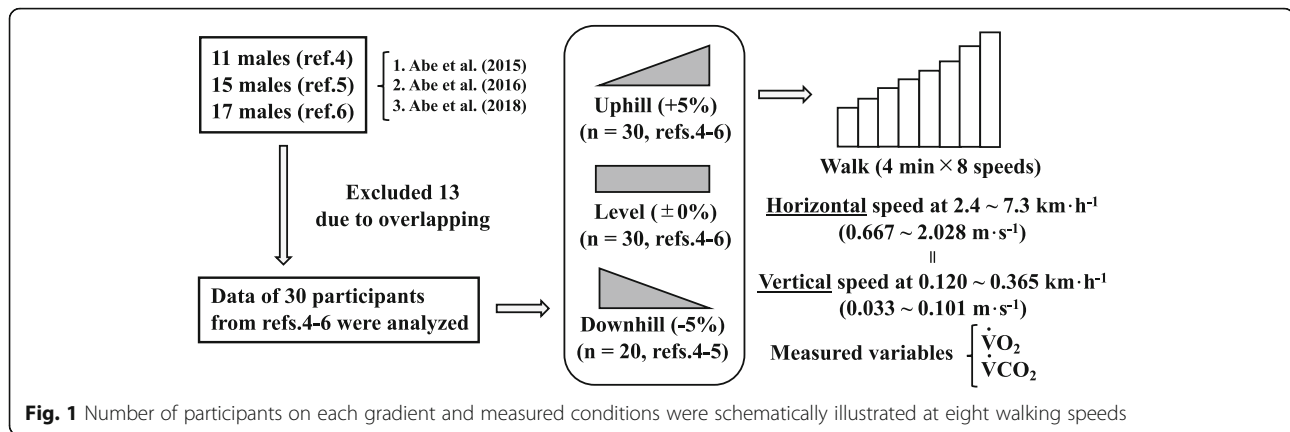
Methods

Participants

As shown in Fig. 1, this study used additional data from already published investigations [4–6] from an entirely different perspective. Since several participants were overlapped among those investigations, the data from the first measurement in those overlapped participants were used in this study. Thirty males were involved in the level and uphill conditions with a mean age of 19.9 ± 1.0 years, stature of 170.5 ± 5.7 cm, and body mass of 59.8 ± 6.8 kg, respectively (mean \pm standard deviation [SD]). Downhill gradient (-5%) was not tested in one of the previous studies [6], so 20 of the 30 males (20.0 ± 1.1 years, 170.0 ± 6.3 cm, and 59.8 ± 5.5 kg) were involved in a downhill condition. An ethical committee of Kyushu Sangyo University approved all procedures of this study (H240324, H27-0002, and H28-0001).

Study procedures

Exercise protocols were also described in Fig. 1. All participants continuously walked on a motor-driven treadmill (LABORDO LXE1200, Senoh, Japan) at eight horizontal walking speeds from 0.667 to $2.028\text{ m}\cdot\text{s}^{-1}$ on the level ($\pm 0\%$) and uphill ($+5\% = +2.862^\circ$) gradients. These horizontal speeds and gradients provided v_{vert} from 0.033 to $0.101\text{ m}\cdot\text{s}^{-1}$ calculated from a following equation [13–16].



$$v_{\text{vert}} = \text{each walking speed} \cdot \sin(2.862^\circ) \quad (1)$$

$$\text{Delta-E} = \frac{1}{\alpha} \cdot 100 \quad (7)$$

Measurements and analysis

Oxygen uptake (VO_2 ; $\text{mL}\cdot\text{kg}^{-1}\cdot\text{min}^{-1}$) and carbon dioxide output (VCO_2 ; $\text{mL}\cdot\text{kg}^{-1}\cdot\text{min}^{-1}$) were continuously measured for 4 min at each speed with a breath-by-breath system (Additional file 1: Figure S1) (AE-310S, Minato Ltd, Japan). The average of VO_2 and VCO_2 for the final 2 min at each speed was used to calculate the energy expenditure (EE; $\text{J}\cdot\text{kg}^{-1}\cdot\text{s}^{-1}$) as follows [27].

$$\text{EE} = \frac{4.186 \cdot (3.869 \cdot \text{VO}_2 + 1.195 \cdot \text{VCO}_2)}{60} \quad (2)$$

ΔEE ($\text{J}\cdot\text{kg}^{-1}\cdot\text{s}^{-1}$) at each v_{vert} was multiplied by BM to obtain the MR_{vert} :

$$\text{MR}_{\text{vert}} = \Delta\text{EE} \cdot \text{BM} \quad (3)$$

P_{mech} was obtained by multiplying the BM, g , and v_{vert} [12–16, 21]:

$$P_{\text{mech}} = \text{BM} \cdot g \cdot v_{\text{vert}} \quad (4)$$

Eff_{vert} is given by the following equation. Because ΔEE was obtained by a subtraction between different gradients, the calculated Eff_{vert} was the net value.

$$\text{Eff}_{\text{vert}} = \frac{P_{\text{mech}}}{\text{MR}_{\text{vert}}} \cdot 100 \quad (5)$$

We also calculated the relationship between P_{mech} and MR_{vert} across eight measured v_{vert} for each participant on both gradients as follows:

$$\text{MR}_{\text{vert}} = a \cdot P_{\text{mech}} + b \quad (6)$$

where a and b are constants. Delta-E is the inverse slope of the regression line given in Eq. 6 [23, 24], so it can be calculated as follows:

Equation 7 means that each individual has only one Delta-E value for each gradient.

Statistical analysis

The efficiency values were compared with one-way repeated measures ANOVA within participants on each gradient. When a significant F value was obtained, it was examined by Bonferroni/Dunn’s post hoc test. Statistical significance was accepted at $p < 0.05$.

Results

Upward Eff_{vert} values (range, 34.1–39.9%) did not differ significantly across measured v_{vert} ($F = 1.045$, $p = 0.403$; Fig. 2a and Additional file 2: Table S1). Downward Eff_{vert} values (range, 48.5–79.6%) were significantly higher at slower v_{vert} than at faster v_{vert} ($F = 5.116$, $p < 0.001$; Fig. 2b and Additional file 2: Table S1). Upward and downward Delta-E values were $35.5 \pm 8.8\%$ and $44.9 \pm 12.8\%$, respectively (Fig. 3). There were significant differences between downward Delta-E and Eff_{vert} (Fig. 2b), but not between upward Delta-E and Eff_{vert} (Fig. 2a).

Discussion

A striking finding of our study was that upward Eff_{vert} values did not vary significantly across the range of measured v_{vert} (Fig. 2a). However, downward Eff_{vert} values were significantly higher at slower v_{vert} than at faster v_{vert} (Fig. 2b). These results fully supported our hypothesis. The results indicated that ΔEE for the upward direction was proportional to v_{vert} . That is, ΔEE for the upward direction can directly be explained by the amount of active muscles generating the accelerating force. This interpretation is consistent with those of some previous studies [18, 21, 22]. Because Eff_{vert} is a “dimensionless” value (%), it can directly be compared with the results of other studies, even if measured speed and/or gradient were different.

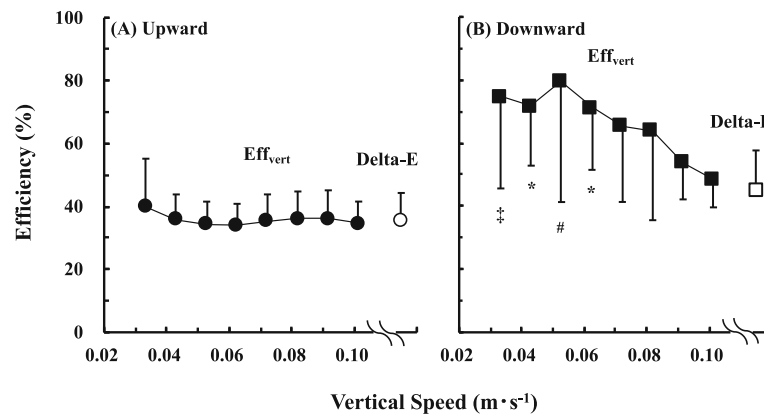


Fig. 2 Upward (a) and downward (b) Eff_{vert} , respectively. † indicates $p < 0.05$ against 0.092, 0.101 $m \cdot s^{-1}$ and Delta-E. * indicates $p < 0.05$ against Delta-E. # indicates $p < 0.05$ against 0.092, 0.101 $m \cdot s^{-1}$, and Delta-E. Data are mean \pm standard deviation (SD)

On the basis of these interpretations, participant’s attribution could not be a limitation. For example, upward Eff_{vert} was significantly improved in schizophrenia patients with gait disturbance by 19.7% after 8-week maximal strength training [12]. This percent increase in Eff_{vert} is not surprising, because more considerable improvement was observed in healthy elderly populations [16] and cardiorespiratory patients [13, 15] after that training. A possible mechanism has been reported to be a high level of stress on all motor units including muscle activation [15]. Of note, these upward Eff_{vert} values in the previous studies were evaluated only at 1.00 $m \cdot s^{-1}$ [12–16].

As far as we know, economical speed (ES) has been the most potential index to evaluate individual walking “ability,” however, it is necessary to obtain the ES using 5–8 sets of metabolic measurements at various speeds [4–8, 11]. Each set of metabolic measurement requires 4–5 min, so the participants need to walk at least for more than 20 min. This could not be a heavy exercise for healthy young participants; however, it may be somewhat heavy for physically poor people, such as prosthetic pedestrians, patients after surgery, obese people, pregnant women, and elderly people to execute the whole sets of metabolic measurements. We found that Eff_{vert} was not dependent on walking speeds, at least from 0.667 to 2.028 $m \cdot s^{-1}$ on the uphill gradient (Fig. 2a), indicating that it can be evaluated at any designated speed. Furthermore, only two sets of metabolic measurements on the level and shallow uphill gradients without kinematic information are required. This could be a significant reduction of participants’ physical strain during metabolic measurement.

It is worth noting that upward Delta-E value was not significantly different from upward Eff_{vert} values at any speed (Fig. 2a). Methodological considerations should be necessary. Previous studies fixed the horizontal walking speed at 1.2–1.3 $m \cdot s^{-1}$ and changed treadmill gradient incrementally [23, 24]. Conversely, we fixed the treadmill gradient at $\pm 5\%$, and varied the walking speed incrementally. The pendular energy transduction between kinetic energy and gravitational potential energy became maximal at around 1.4 $m \cdot s^{-1}$ [28, 29]. The minimum of the U-shaped relationship between CoT and horizontal walking speed occurs at around 1.4 $m \cdot s^{-1}$, irrespective of the gradient [4–6]. These previous findings suggest that the grade incremental protocol may underestimate the EE (\approx higher Delta-E). However, Delta-E reflects the inverse of an increasing rate of mechanical power output to energy consumption rate, so it may not be influenced by walking speed. Indeed, upward Delta-E of $35.5 \pm 8.8\%$

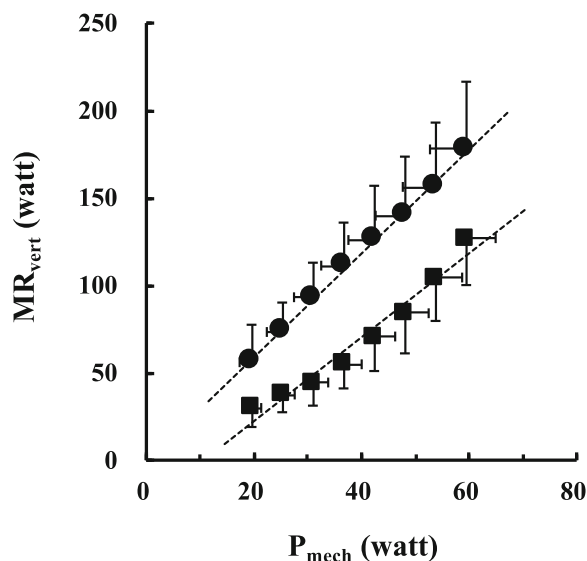


Fig. 3 Upward (circles) and downward (squares) delta efficiency (Delta-E) was calculated from the inverse of the relationships of P_{mech} to MR_{vert} across eight measured vertical speed (v_{vert}). $MR_{vert} = 2.968 \cdot P_{mech} - 0.573$ ($r = 0.999$) for upward Delta-E, and $MR_{vert} = 2.399 \cdot P_{mech} - 25.665$ ($r = 0.981$) for downward Delta-E, respectively. Data are mean \pm SD

was in good agreement with the result of a previous study in young adults involving both genders [23]. Given these considerations, our speed incremental protocol would be equivalent to the grade incremental protocol. We need to remind that Delta-E always requires the inverse “slope” of the regression line of MR_{vert} to P_{mech} (Eq. 6). That is, a series of metabolic measurements are necessary to obtain the “slope” from which it is calculated, so it is practically available only for fit populations, but not for clinical patients.

A trend for significantly higher downward Eff_{vert} values at slower v_{vert} than at faster v_{vert} (Fig. 2b and Additional file 2: Table S1) was consistent with a previous result [25], indicating that the amount of active muscles needed to generate the accelerating force could not be proportional to v_{vert} during downhill walking. Indeed, “negative” work rather than “positive” work becomes dominant during downhill walking [25, 26]. The recovery rate of pendular energy transduction gradually decreased at faster v_{vert} [26]. This individual variation of the recovery rate of the pendular energy transduction is associated with the muscular EE during negative and positive work. Indeed, the EE of negative work is one third of that of “positive” work [30]. Stored elastic energy in the Achilles tendon and *gastrocnemius medialis* can be utilized even during level walking at 0.75 m s^{-1} [20]. These interactions would be expected to vary considerably between individuals during downhill walking, given that relatively greater variations were observed in downward Eff_{vert} values than in upward Eff_{vert} values (Fig. 2b).

Conclusions

It is possible to evaluate vertical component of walking efficiency without kinematic information. Upward Eff_{vert} values were nearly constant across a wide range of v_{vert} , suggesting that EE to lift the body could be proportional to v_{vert} . Therefore, upward Eff_{vert} should be useful for people with poor physical fitness to evaluate their gait characteristics. This is because only two metabolic measurements are required to obtain individual upward Eff_{vert} on the level and uphill gradients at any voluntary speed. However, this interpretation could not be applied to downhill walking. Delta-E was compatible with upward Eff_{vert} , but not with most of the downward Eff_{vert} .

Supplementary information

Supplementary information accompanies this paper at <https://doi.org/10.1186/s40101-019-0211-4>.

Additional file 1: Figure S1. Relationships between cardiorespiratory responses and walking speed at different gradients.

Additional file 2: Table S1. Summary of measured and calculated variables at each speed. P_{mech} : mechanical power output for vertical directions, ΔEE : differences of energy expenditure between uphill and

level gradients or between level and downhill gradients, MR_{vert} : metabolic rate for vertical directions, and Eff_{vert} : vertical efficiency. Values are mean (\pm SD).

Abbreviations

ANOVA: Analysis of variance; BM: Body mass; CoT: Energy cost of transport per unit distance; Delta-E: Delta efficiency; EE: Whole-body energy expenditure; Eff_{vert} : Vertical component of net walking efficiency; MR_{vert} : Vertical component of metabolic rate; P_{mech} : Vertical component of mechanical power output; VCO_2 : Carbon dioxide output; VO_2 : Oxygen uptake; v_{vert} : Vertical component of walking speed; ΔEE : Difference of EE between the level and uphill/downhill gradients

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Authors' contributions

DA, YF, and MH designed the study and interpreted the results. DA performed measurements and data analysis and prepared the tables, figures, and first manuscript. YF and MH revised the manuscript. All authors have read and approved the final manuscript.

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Availability of data and materials

All data used in this study were summarized and in the supplementary information.

Ethics approval and consent to participate

In accordance with the Declaration of Helsinki, all participants were provided all information about the purposes, benefits, possible risks, and experimental protocols. A written informed consent was obtained from all participants. An ethical committee established in Kyushu Sangyo University approved all procedures of this study (H240324, H27-0002, and H28-0001).

Consent for publication

Not applicable

Competing interests

The authors declare that they have no competing interests.

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